



Canadian Space
Agency

Agence spatiale
canadienne



CSA-NEOSSAT-MAN-0002

Canadian Space Agency
Satellite Operations and Infrastructure

NEOSSat FITS Image User's Guide

FITS Processor Version 2.07

December 2018

Approvals

Approved by	Signature	Name (Print)	Date
Author	_____	J.F. Cusson, S. Hasaj	December 2018
Reviewed By	_____	V. Abbasi	_____
Reviewed By	_____	J.F. Cusson	_____
Approved By	_____	M. Doyon	_____
Product Assurance	_____	M. Bennett	_____

Revision History

Rev.	Description	Initials	Date
Draft	Initial Release based on FITS Processor 2.06 (beta)	VA	12 Oct 2018
2.07	Updates for FITS Processor 2.07	SH	07 Dec 2018

Table of Contents

1	Scope.....	6
1.1	Purpose and Scope.....	6
1.2	Document Overview	6
2	Documents	7
2.1	Applicable Documents	7
2.2	Reference Documents.....	7
3	Version Information.....	8
3.1	Current Version Identification	8
4	Image SPECIFICATIONS, and Science CCD Frame.....	9
5	FITS Format	11
5.1	General.....	11
5.2	Primary Header Keyword Records Summary.....	11
5.3	Padding	19
5.4	Extension Header Keyword Records Summary.....	19
5.4.1	Raw Voltages Binary Table Summary.....	20
5.4.2	Raw Telemetry Binary Table Summary	21
5.4.3	ACS History Binary Table Summary.....	23
5.4.4	CCD & Transmitters History Binary Table Summary	25
5.4.5	Read List Binary Table Summary.....	27

LIST OF TABLES AND FIGURES

Table 1: Reference Documents.....	7
Table 2 : Raw Voltages Binary Table Header	20
Table 3 : Raw Voltages Binary Table Example	21
Table 4 : Raw Telemetry Binary Table Header	21
Table 5 : Raw Telemetry Binary Table Example	22
Table 6 : ACS history Binary Table Header.....	23
Table 7 : ACS History Binary Table Example	24
Table 8 : CCD History Binary Table Header	25
Table 9 : CCD History Binary Table Example	26
Table 10 : Read List Binary Table Header.....	27
Table 11 : Read List Binary Table Example.....	27
Figure 1: Explanation of the satellite image coordinates	9

1 SCOPE

1.1 Purpose and Scope

This document presents a user's guide to the NEOSSat FITS Images.

1.2 Document Overview

First, some reference document and basic version information is provided.

Then, an overview of the NEOSSat CCD and image coordinates is provided.

Finally, the detailed format of the NEOSSat FITS image file is provided. Details of the primary header (i.e., the 'FITS header') are specified, as well as binary extensions that contain unprocessed raw telemetry data, embedded in every FITS image file. These binary extensions could be read with programs such as Matlab.

2 DOCUMENTS

2.1 Applicable Documents

None

2.2 Reference Documents

Table 1: Reference Documents

RD No.	Document Number	Document Title	Rev. No.	Date
RD-1.	fits_standard30aa.pdf	Definition of the Flexible Image Transport System (FITS), FITS Working Group. Available from http://fits.gsfc.nasa.gov/fits_standard.html	3.0	10 July, 2008

3 VERSION INFORMATION

3.1 Current Version Identification

- This document applies to version 2.07 of NEOSSat FITS Production Software.

Future updates in the NEOSSat FITS production software could add/remove/change header information or otherwise affect performance. The header tag CONV_SW indicates which version of the FITS Converter ground segment software was used to create the FITS image. Tags ROE_SW and S921_SW indicate flight software versions used to create the FITS image.

4 IMAGE SPECIFICATIONS, AND SCIENCE CCD FRAME

The following illustrations provides the basic specifications of NEOSSat image coordinates, either from Science ROE or Star Tracker ROE. Depending on onboard settings, an image may be a subset of these coordinates, or even may be composed of a mosaic of multiple smaller sub-images.

Note that in some case (e.g. binned image) the coordinates may be transformed.

Note also that depending on the direction of the readout (opamp setting), it is possible to have images which coordinates will go outside these boundaries, mainly for diagnostic purposes since extra pixels values will not correspond to an actual CCD pixel but rather be "overscan" data.

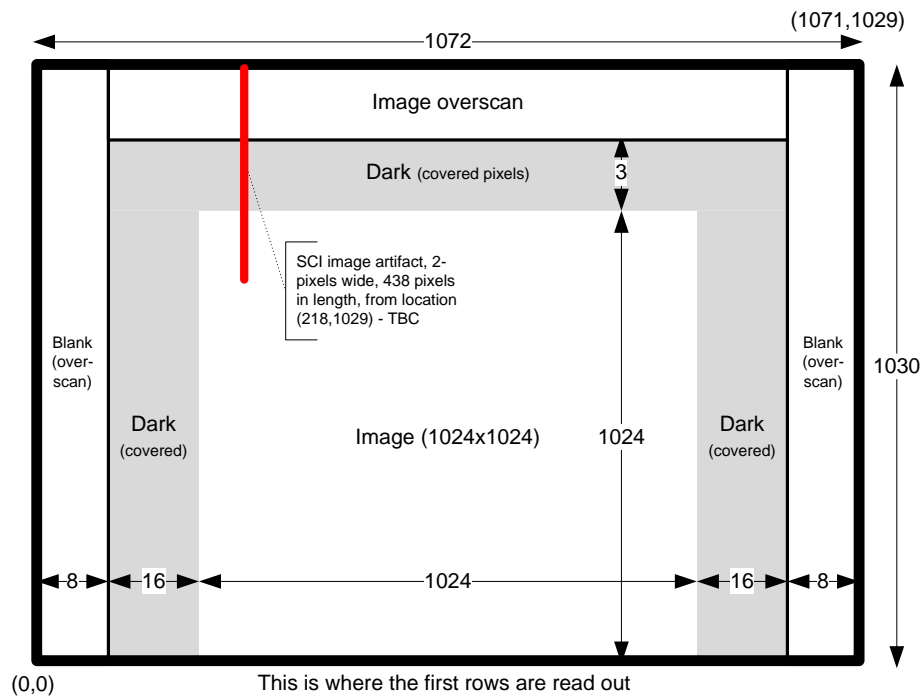
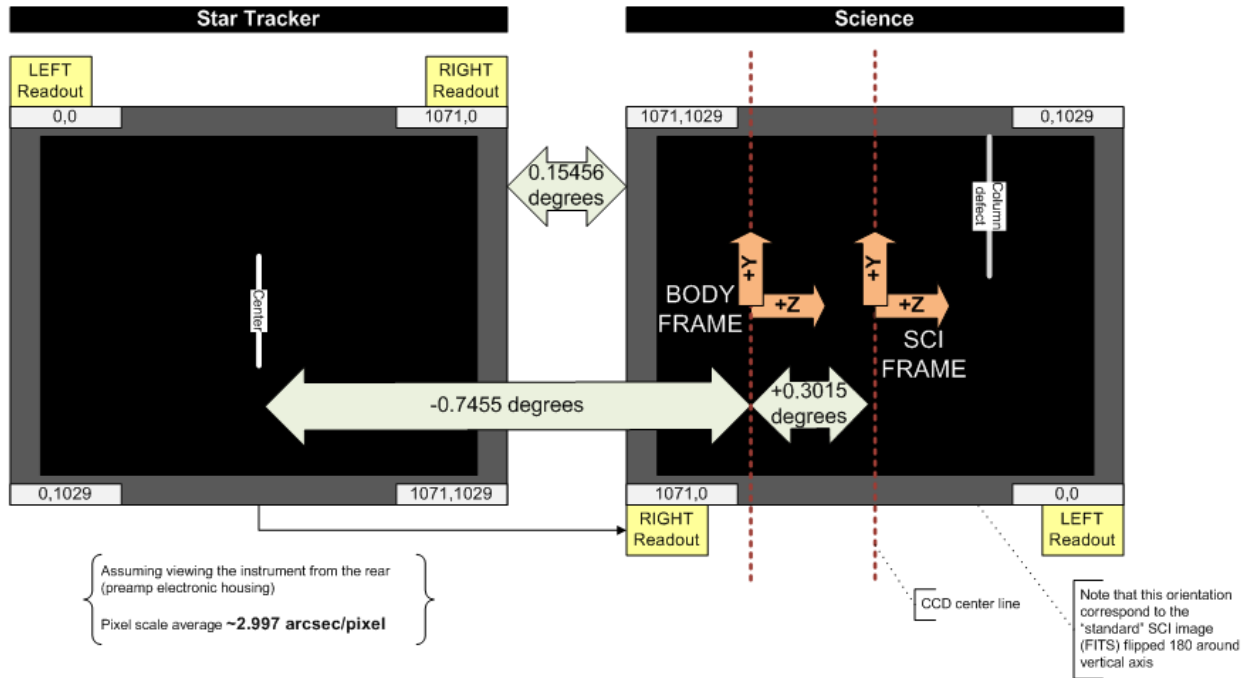


Figure 1: Explanation of the satellite image coordinates

The field of view within the 1024 x 1024 area 'seeing' space, is 0.86 degrees. Therefore, each pixel correspond approximately to 3 arc-seconds.

The Science CCD frame is defined with its origin at the center of the 1024x1024 CCD area 'seeing space'. It is aligned in X and Y with the body frame, and offsetted by 0.3015 degrees along +Z.



5 FITS FORMAT

5.1 General

The application generates Multi-Extension FITS (MEF), which means it consists of the primary header and data unit (HDU), plus extensions containing raw meta-data. The purpose of the extensions is to allow access to raw, un-processed and complete data if necessary (e.g. for verification of data displayed in the primary header, or to get more resolution than what would be displayed in the primary header).

Enough header blocks (2880 bytes each) are created to contain all image meta-data, and the primary data array contains the image pixels (16-bit for each pixel), padded at the end with zeros if necessary so that 2880-bytes data-block boundaries are respected.

Each record strictly follows FITS standard, :

1. Keyword name is uppercase and fits in first 8 bytes (bytes 1 to 8) (and is padded with spaces to be 8 bytes long). *Note that in some case we use leading zeros for indices, which is specifically forbidden in the FITS standard (e.g. CCDCLK01 instead of CCDCLK1).*
2. When a value follows, next two bytes (bytes 9 and 10) are “= ” (equal sign plus a space);
3. Remaining bytes (11 to 80) contains the value in ASCII text and a comment preceded by “/”.

5.2 Primary Header Keyword Records Summary

Keyword Record	Unit	Description
SIMPLE	String	Set to True (“T”), must be first record for standard FITS
BITPIX	bits	Bits per pixel for image data. Set to 16 in our case
NAXIS	Axis	Number of axis in the represented image. Our image is a 2-D CCD plane, so this value is set to 2
NAXIS1	Pixels	Size of image – Xaxis, in units of pixels. Note that in our case, depending on the read list, an “image” may be a mosaic of several sub-images from an exposure. NAXIS1 and NAXIS2 provide the outside boundary of a composite image containing all sub-images
NAXIS2	Pixels	Size of image – Yaxis, in units of pixels. See NAXIS1 for more details
BSCALE	Factor	Data scaling. Set to ‘1’
BZERO	Adu	zero def of pixel (for unsigned short). Set to 32768
IMAGE		Placeholder for image specification header
BIASSEC	Pixel range	Overscan area, in image coordinates [colStart:colEnd,rowSt,rowEnd]
TRIMSEC	Pixel range	Science area, in image coordinates [colStart:colEnd,rowSt,rowEnd]
DATASEC	Pixel range	Science area, in image coordinates [colStart:colEnd,rowSt,rowEnd]
CCDSEC	Pixel range	Science data coordinates in CCD system [colStart:colEnd,rowSt,rowEnd]. Per image coordinate conventions, indices start at 1, not zero.
CORNER1X	Column	Image coordinates in CCD system , lower left corner column. Indices starts at zero, and may be negative to include overscan. See section “Image Coordinates” for more details
CORNER1Y	Row	Image coord in CCD system , Lower Left Corner row

CORNER2X	Column	Image coord in CCD system , Upper Right Corner column
CORNER2Y	Row	Image coord in CCD system , Upper Right Corner row
OPAMP	String	Read out chain used: Left, right, both. Note that if this image is composed of sub-images, individual sub-images could have different OPAMP settings. Individual OPAMP settings are not provided in the FITS header.
GAIN	String	Estimated CCD amplifier gain in electrons per analog unit. When OPAMP String equals "both", two comma-separate values are specified (GAIN_LEFT, GAIN_RIGHT).
RDNOISE	String	Estimated CCD readout noise in electrons. When OPAMP String equals "both", two comma-separate values are specified (RDNOISE_LEFT, RDNOISE_RIGHT). If binning is in effect, multiply the RDNOISE by the binning factor, as binning is implemented on the CCD as a hardware summation of the contributing pixels, (charge from group of pixel cells dumped into the accumulators for the row/column).
XBINNING	Pixels	Number of grouped CCD pixels, on the X-axis (binning, X)
YBINNING	Pixels	Number of grouped CCD pixels, on the Y-axis (binning, Y)
COMPR_AL	String	Identification of the algorithm used for compressing image data (by the spacecraft), or "Uncompress" if compression was not used.
COMP_SET	Integer	Compression settings, as reported by the spacecraft. For now, only value '1' is expected, as there is only one possible setting. If image is not compressed, this record will specify "N/A".
N_SUBIMG	Counter	Number of sub-images composing this image. Note that if there is only one main image, this record will be set to zero. If there are sub-images, there will be at least two of them, so this record possible values are 0, then 2 to the maximum number of sub-images. Coordinates of every sub-images are given in subsequent fields, with first sub-image identified as sub-image zero. Note that the maximum number of sub-images is 10.
RGN nnn X1	Column	Sub-image nnn (starting at zero) , x position of bottom left corner in CCD coordinate system.
RGN nnn Y1	Row	Sub-image nnn (starting at zero) , y position of bottom left corner in CCD coordinate system.
RGN nnn X2	Column	Sub-image nnn (starting at zero) , x position of top right corner in CCD coordinate system.
RGN nnn Y2	Row	Sub-image nnn (starting at zero) , y position of top right corner in CCD coordinate system.
OVERSCAN	Flag	Indicates whether this image contains overscan pixel values (lying outside of the CCD area, therefore not corresponding to actual CCD pixels). Possible values are zero (for NO) and non-zero (for OVERSCAN DATA present). For the moment, this field only provide information if the generated image is greater than 1072x1032. Note that the standard overscan columns on the edge of the CCD chip are not counted as 'overscan' per se.
CREATOR	String	Origin of FITS file. Fixed to "NEOSSat".
TELESCOP	String	Identification of the telescope used to take the image. Fixed to "NEOSSat".
SHUTTER	String	Shutter status (OPEN or CLOSED). The reported status number is given, followed by a description string (e.g. '0 (open)'). Dark frame images for NEOSSat are specified by the shutter being closed.
SHUT_AGE	Seconds	Specifies the time elapsed since the SHUTTER state is in effect. Note that a negative number represents time in the past (which will normally be the case).

DETECTOR	String	Identification of the detector being used (Science or Star Tracker) to generate this image.
TIMING		Placeholder for timing specification header
TIMESYS	String	Time scale specification (set to 'UTC')
EXPOSURE	Seconds	Actual Length of exposure
AEXPTIME	Seconds	Actual length of exposure. This record is identical to EXPOSURE, and was added because needed by MPS using this particular keyword.
REXPTIME	Seconds	Request length of exposure.
DATE-OBS	Date & Time	Date of observation (start of exposure). Format is YYYY-MM-DDT _{HH} :MM:SS.sss.
TIME-OBS	Date & Time	Time of observation (start of exposure). Format is YY-MM-DDT _{HH} :MM:SS.sss.
JD-OBS	JD	Date of observation (start of exposure). Expressed in Julian Date (continuous count of days since noon Universal Time on Jan 1 st , 4713 BCE on the Julian calendar).
R_EXP_S	Date & Time	Requested exposure start time. Format is YY-MM-DDT _{HH} :MM:SS.sss. Note that the actual exposure start time may differ from the commanded one.
A_EXP_S	Date & Time	Actual exposure start time. Format is YYYY-MM-DDT _{HH} :MM:SS.sss. This is a duplicate of record DATE-OBS, required by MPS.
LEN_FLU	Seconds	Length of the CCD FLUSH operation in the process of taking this image.
LEN_TRAN	Seconds	Length of the frame transfer operation in the process of taking this image.
LEN_READ	Seconds	Length of the frame transfer and readout operations in the process of taking this image.
LEN_PROC	Seconds	Length of post-processing operations in the process of taking this image.
LENDELAY	Seconds	Length of the delay between exposure command execution and the first operation (CCD FLUSH) involved in taking this image.
POINTING		Placeholder for pointing specification header
EQUINOX	Year	Equatorial coordinates. Fixed to 2000.0 (for J2000)
MODE	String	Spacecraft Attitude Control System (ACS) pointing state. The number (as specified in the spacecraft ACS state diagram) is given, followed by a string identifying the mode. The key imaging modes for NEOSSat are: 16-FINE_POINT : indicates NEOSSat is stabilized relative to fixed stars 14-FINE_SLEW : indicates NEOSSat is slewing to track a moving object. The slew rate can be determined using RA_VEL, DEC_VEL, ROL_VEL. Dark frame images (taken with the shutter closed) typically cannot be taken in these modes and so mode should be ignored on those cases. Non-dark images that are in neither FINE_POINT nor FINE_SLEW are typically not useful for science purposes.
MODETIME	Seconds	Time elapsed since the spacecraft entered the specified MODE. This number, expressed in seconds, will always be negative as it represents time in the past.
CMD	Radians	Commanded spacecraft pointing, celestial coordinates, in Science CCD frame. Format = 'RA=x.xxx DEC=x.xxx ROLL=x.xxx'
CMDRA	hrs,min,sec	Commanded Right Ascension (RA), in Science CCD frame. Format is 'hh mm ss.s' where hh=hours, mm=minutes and ss.s=decimal seconds
CMDDEC	deg,min,sec	Commanded Declination (DEC), in Science CCD frame. Format is 'dd mm ss.s' where dd=degrees, mm=minutes and ss.s=decimal seconds
CMDROL	Degrees	Commanded Roll, in degrees, in Science CCD frame.

CMDQ0	n/a	Commanded quaternion $qp[0]$. Represents QB, or "i" in the "scalar,i,j,k" notation.
CMDQ1	n/a	Commanded quaternion $qp[1]$. Represents QC, or "j".
CMDQ2	n/a	Commanded quaternion $qp[2]$. Represents QD, or "k".
CMDQ3	n/a	Commanded quaternion $qp[3]$. Represents QA, or "scalar".
OBJCTRA	hrs,min,sec	Actual Right Ascension (RA) at start of exposure, in Science CCD frame. Format is 'hh mm ss.s' where hh=hours, mm=minutes and ss.s=decimal seconds.
OBJCTDEC	deg,min,sec	Actual Declination (DEC) at start of exposure, in Science CCD frame. Format is 'dd mm ss.s' where dd=degrees, mm=minutes and ss.s=decimal seconds.
OBJCTROL	degrees	Actual Roll at start of exposure, in Science CCD frame, provided in degrees.
RA	hrs:min:sec	Actual Right Ascension (RA). Same as OBJCTRA using 'hh:mm:ss.s' format, where hh=hours, mm=minutes and ss.s=decimal seconds.
DEC	deg:min:sec	Actual Declination (DEC). Same as OBJCTDEC using 'dd:mm:ss.s' format, where dd=degrees, mm=minutes and ss.s=decimal seconds.
ELA_MIN	degrees	Minimum Earth limb angle attained while exposing, from an axis perpendicular to the image plane.
ELA_MAX	degrees	Maximum Earth limb angle attained while exposing, from an axis perpendicular to the image plane.
ELA_ANG	degrees	Angle to Earth Limb while exposing. NOTE that at this moment we populate this record with ELA_MIN value. It is TBC if this is adequate.
SUN_MIN	degrees	Minimum Sun angle attained while exposing, from an axis perpendicular to the image plane.
SUN_MAX	degrees	Maximum Sun angle attained while exposing, from an axis perpendicular to the image plane.
HIST_NB	count	Number of ACS history points (i.e. number of samples of pointing data recorded and provided while exposing) that follows this field. Note that whenever Star Tracker is operating (e.g. in fine pointing modes), the ACS history will contain data exclusively computed from Star Tracker solutions, and provided at the same rate as Star Tracker images (typically between 0.5 and 1Hz). When Star Tracker is not operating, estimated EKF data at full rate (5Hz) is provided.
DELTA_nnn	seconds	Time difference between this pointing data sample (identified by a sequence number <i>nnn</i> starting at 000) and the start of exposure. The first sample can be before the actual exposure start, represented by a negative number here. This is part of the <i>ACS history</i> .
DEV_nnn	arc-sec	A sample of the spacecraft pointing wander while exposing. Expressed in rotations around X/Y/Z body frame axis, relative to the first attitude data point (therefore DEV_000 will always be "0 0 0"). This is part of the <i>ACS history</i> .
VEL_nnn	rad/sec	A sample of the spacecraft estimated velocity. Expressed around X/Y/Z body frame axis at instantaneous time. This is part of the <i>ACS history</i> .
RA_VEL	hours/s	Signed angular slew velocity in Right Ascension (RA) at midpoint of the exposure.
DEC_VEL	degrees/s	Signed angular slew velocity in Declination at midpoint of the exposure.
ROL_VEL	degrees/s	Signed angular slew velocity in Roll at midpoint of the exposure.
ENVIRO		Placeholder for environment data header
TEMP_CCD	kelvins	Temperature of CCD. If the CCD temperature history is available, the temperature will be the average of all temperature samples taken while

		exposing (+/- 1 second). If the CCD temperature history is not available, this value is set from the temperature sample sent by the imager after readout (which will be several seconds after exposure, more than 30 seconds for a full image).
CCD-TEMP	Celsius	Temperature of CCD in Celsius. Derived from the value of TEMP_CCD, using formula $CCD-TEMP = TEMP_CCD - 273.15$.
CCDT_NB	Count	Number of samples included in the CCD temperature history, that follows this field.
CCDT_ <i>nnn</i>	Various	Provides data related to a specific sample of the CCD temperature history, in addition to the state of the transmitters. Format = ' S . SSS KKK . K TX- TX+ ' where S . SSS = Number of seconds between this sample and start of exposure (negative if prior exposure). KKK . K = Temperature of the CCD in Kelvins. TX- = "ON" if minus_Y transmitter module is powered ON, "OFF" if powered OFF, "N/A" if status is unknown. TX+ = Same as TX-. NOTE THAT a module being powered ON does not necessarily mean that data transmission is underway. Example: ' 71 . 302 230 . 5 OFF OFF' means that this sample was taken 71.302 seconds after start of exposure, the CCD was at 230.5K, and both transmitters were OFF. Note that when this CCD temperature history is available, all temperature with a number of seconds from exposure between -1 and +(exposure time+1) are retained and averaged to produce the TEMP_CCD value.
TEMP_ROE	kelvins	Temperature of the imager (Read-Out Electronics or ROE) after image exposure and readout.
TEMP_AMP	kelvins	Temperature of the pre-amplifier electronics after image exposure and readout.
TEMP_PLD	kelvins	Temperature of the imager (ROE) Programmable Logic Device circuit (FPGA) after image exposure and readout.
P28V	volts	+28V supply sensor reading.
P24V	volts	+24V supply sensor reading.
P12V	volts	+12V supply sensor reading.
N12V	volts	-12V supply sensor reading.
P10V	volts	+10V supply sensor reading.
N10V	volts	-10V supply sensor reading.
P5V	volts	+5V supply sensor reading.
N5V	volts	-5V supply sensor reading.
P5VD	volts	+5V differential supply sensor reading.
P3V3D	volts	+3.3V supply sensor reading.
vTG	volts	TG voltage reading.
CCDBIAS0	volts	Voltage for CCD clocking line - IMG_L_BIAS
CCDBIAS1	volts	Voltage for CCD clocking line - IMG_R_BIAS
CCDBIAS2	volts	Voltage for CCD clocking line - ODR
CCDBIAS3	volts	Voltage for CCD clocking line - ODL
CCDBIAS4	volts	Voltage for CCD clocking line - RDR
CCDBIAS5	volts	Voltage for CCD clocking line - RDL
CCDBIAS6	volts	Voltage for CCD clocking line - OG
CCDBIAS7	volts	Voltage for CCD clocking line - ABG
CCDCLK00	volts	Voltage for CCD clocking line - IPC-
CCDCLK01	volts	Voltage for CCD clocking line - IPC+

CCDCLK02	volts	Voltage for CCD clocking line - RG-
CCDCLK03	volts	Voltage for CCD clocking line - RG+
CCDCLK04	volts	Voltage for CCD clocking line - S- R1L/R2L/R3L
CCDCLK05	volts	Voltage for CCD clocking line - S+ R1R/R2R/R3R
CCDCLK06	volts	Voltage for CCD clocking line - DG-
CCDCLK07	volts	Voltage for CCD clocking line - DG+
CCDCLK08	volts	Voltage for CCD clocking line - TG-
CCDCLK09	volts	Voltage for CCD clocking line - TG+
CCDCLK10	volts	Voltage for CCD clocking line - P1- ST1-/IM1-
CCDCLK11	volts	Voltage for CCD clocking line - P1+ ST1+/IM1+
CCDCLK12	volts	Voltage for CCD clocking line - P2- ST2-/IM2-
CCDCLK13	volts	Voltage for CCD clocking line - P2+ ST2+/IM2+
CCDCLK14	volts	Voltage for CCD clocking line - P3- ST3-/IM3-
CCDCLK15	volts	Voltage for CCD clocking line - P3+ ST3+/IM3+
MPS		Placeholder for the MPS section header
OBJECT	String	Prime object name (specified by the user)
OBSERVER	String	HEOSS NESS ASTRO (specified by the user)
M1	Tbd	Future Use
M2	String	State Vector Solution Status, specifying the source of the state vector data (from GPS telemetry or .navsol). Currently one of three Status': FINE_TLM_T, FINE_NAVSOL_T, NO_SOLUTION_T, where 'T' represents the largest timestep, in seconds, between GPS data points used for interpolation of solution. (T < 5 indicate nominal GPS data availability)
EPOS1_1	km	ECEF Position at Exp start, X-component
EPOS1_2	km	ECEF Position at Exp start, Y-Component
EPOS1_3	km	ECEF Position at Exp start, Z-Component
EPOS2_1	km	ECEF Position at Exp middle, X-component
EPOS2_2	km	ECEF Position at Exp middle, Y-component
EPOS2_3	km	ECEF Position at Exp middle, Z-component
EPOS3_1	km	ECEF Position at Exp end, X-component
EPOS3_2	km	ECEF Position at Exp end, Y-component
EPOS3_3	km	ECEF Position at Exp end, Z-component
JPOS1_1	km	J2000 Position at Exp start, X-component
JPOS1_2	km	J2000 Position at Exp start, Y-component
JPOS1_3	km	J2000 Position at Exp start, Z-component
JVEL1_1	km/s	J2000 Velocity at Exp start, X-component
JVEL1_2	km/s	J2000 Velocity at Exp start, Y-component
JVEL1_3	km/s	J2000 Velocity at Exp start, Z-component
JPOS2_1	km	J2000 Position at Exp middle, X-component
JPOS2_2	km	J2000 Position at Exp middle, Y-component
JPOS2_3	km	J2000 Position at Exp middle, Z-component
JVEL2_1	km/s	J2000 Velocity at Exp middle, X-component
JVEL2_2	km/s	J2000 Velocity at Exp middle, Y-component
JVEL2_3	km/s	J2000 Velocity at Exp middle, Z-component
JPOS3_1	km	J2000 Position at Exp end, X-component
JPOS3_2	km	J2000 Position at Exp end, Y-component
JPOS3_3	km	J2000 Position at Exp end, Z-component
JVEL3_1	km/s	J2000 Velocity at Exp end, X-component
JVEL3_2	km/s	J2000 Velocity at Exp end, Y-component
JVEL3_3	km/s	J2000 Velocity at Exp end, Z-component
EVEL3_1	km/s	ECEF Velocity at Exp end, X-component
EVEL3_2	km/s	ECEF Velocity at Exp end, Y-component

EVEL3_3	km/s	ECEF Velocity at Exp end, Z-component
EVEL2_1	km/s	ECEF Velocity at Exp middle, X-component
EVEL2_2	km/s	ECEF Velocity at Exp middle, Y-component
EVEL2_3	km/s	ECEF Velocity at Exp middle, Z-component
EVEL1_1	km/s	ECEF Velocity at Exp start, X-component
EVEL1_2	km/s	ECEF Velocity at Exp start, Y-component
EVEL1_3	km/s	ECEF Velocity at Exp start, Z-component
DIAG		Placeholder for diagnostic section header
ROE_SW	String	Identification of the imager (Read-Out Electronics or "ROE") software version running at the time the image was taken.
S921_SW	String	Identification of the C&DH flight software version running at the time the image was taken.
CONV_SW	String	Identification of the version of the ground software used to convert raw science data into this FITS image (FITS Processor version).
TMFILE n	String	$n=0..00$. Provides name of source telemetry file. As data for an image can be contained in multiple telemetry files (usually no more than 2 consecutive files), the name of each one is given here (e.g. <code>\TMFILE0='NEOS_20141852225H.VC1'</code> , <code>\TMFILE1='NEOS_20141852355H.VC1'</code>)
META_TLM	String	Indicates if image telemetry meta-data packet was accompanying this image. Possible values are "OK" or "MISSING". If missing, some records in the header won't be filled: <ul style="list-style-type: none"> • TEMP_AMP, TEMP_CCD, TEMP_ROE • P28V, P24V... TG sense
META_TIM	String	Indicates if image timing meta-data packet was accompanying this image. Possible values are "OK" or "MISSING". If missing, some records in the header won't be filled: <ul style="list-style-type: none"> • EXPOSURE, AEXPTIME • LENDELAY, LEN_FLU, LEN_TRAN, LEN_READ, LEN_PROC • R_EXP_S, A_EXP_S • TIME_OBS, DATE_OBS, JD_OBS
META_ACS	String	Indicates if ACS history meta-data packet was accompanying this image. Possible values are "OK" or "MISSING". If missing, some records in the header won't be filled: <ul style="list-style-type: none"> • HIST_NB • MODE • CMD • CMDRA, CMDDEC, CMDROL • CMDQ0 to CMDQ3 • MINEARTH, MAXEARTH • MINSUN, MAXSUN • OBJRA, OBJDEC, OBJROL • SHUTTER • Wander data
META_CCD	String	Indicates if CCD history meta-data packet was accompanying this image. Possible values are "OK" or "MISSING". If missing, some records in the header won't be filled: <ul style="list-style-type: none"> • CCDT_NB • CCD history data (including TX state)

		<i>Note also that if META_CCD is MISSING, the value of field TEMP_CCD will be that of TEMP_CCD returned by META_TLM, which is a sample taken several seconds after exposure (less accurate), instead of being calculated from an average of CCD temperature history during exposure.</i>
META_VLT	String	Indicates if voltages meta-data packet was accompanying this image. Possible values are "OK" or "MISSING". If missing, some records in the header won't be filled: <ul style="list-style-type: none"> • CCDBIAS0..7 • CCDCLK0..15 • CCDBIAS0_IMG_L_BIAS_RAW • ... • CCDCLK15_P3P_ST3P_IM3P_RAW
META_FSW	String	Indicates if SW Versions meta-data packet was accompanying this image. Possible values are "OK" or "MISSING". If missing, some records in the header won't be filled: <ul style="list-style-type: none"> • S921_SW • ROE_SW
META_RDL	String	Indicates if image read list meta-data packet was accompanying this image. Possible values are "OK" or "MISSING". If missing, some records in the header won't be filled or will be filled with default values not necessarily corresponding to actual image specifications: <ul style="list-style-type: none"> • NAXIS1, NAXIS2 • OPAMP • GAIN • XBINNING, YBINNING • NYSCAN • CORNER1_X, CORNER2_X, CORNER1_Y, CORNER2_Y and the decoding software will not be able to determine the specification of the image (i.e. size, coordinates, sub-rasters...) so there is a high probability that the image displayed will be incoherent.
IMGSTATE	String	An indication if the data received from the spacecraft and decoded is complete for this image. Possible values are ' NOT_VERIFIED ', ' INCOMPLETE ', ' COMPLETE ' and ' HAS_ZEROS ', where: <p>NOT_VERIFIED = The FITS processor was not able to determine the state of the image (not a nominal case).</p> <p>INCOMPLETE = Not all expected pixel values for this image were extracted from telemetry. There will be missing data within the image.</p> <p>COMPLETE = All expected data have been read and used to create the image. There are no pixel value that have been seen at value zero.</p> <p>HAS_ZEROS = All expected data have been read, however some pixel have zero values, which is not a nominal case for images taken with the spacecraft.</p>
IMG_PERC	0-100%	Percentage of completion of the image (i.e. number of pixels read from telemetry vs total number of pixels needed to complete the image). A value of less than 100% means that some pixel values were 'lost' in the delivery process from space or decoding. Note that this percentage does not include image meta-data.
NB_0_PIX	Nb pixels	Number of pixel that have exactly the value 0 (or black pixel). Note that a value different than zero indicates a non-nominal situation, except for specific test images taken on the flatsat.

FRM_SEQ	String	Indicates whether raw telemetry transfer frame sequence (Virtual Channel Counter), while dumping this image, was continuous or not. Possible values are "OK" or " <i>n</i> ANOMALIES" where <i>n</i> gives the number of "holes" in the sequence. These anomalies would be signatures for downlink problems. If anomalies, we can expect that some pixel data will be missing (see IMGSTATE and IMG_PERC). The application will not detected missing frame at the beginning or at the end of the image.
PKT_SEQ	String	Indicates whether raw telemetry packet sequence counter, while dumping this image from the spacecraft, was continuous or not. Possible values are "OK" or " <i>n</i> ANOMALIES" where <i>n</i> gives the number of "holes" in the sequence. These anomalies would be signatures for downlink problems. If anomalies, we can expect that some pixel data will be missing (see IMGSTATE and IMG_PERC). The application will not detected missing frame at the beginning or at the end of the image.
EXTEND		Set at value "T" to specify extension HDU exists
END	N/A	Specifies the end of the primary header

5.3 Padding

FITS files are composed of blocks of fixed length, which need to be padded if data specific to each block do not fill it completely.

The primary header block is padded with spaces character (' '), while the pixel values block and the binary tables with 0x00 bytes.

5.4 Extension Header Keyword Records Summary

Each Neossat Science FITS file created by the FITS processor, in addition to the primary header and pixel values, includes binary extensions containing raw meta-data, as sent by the spacecraft. Data contained in binary extensions can be extracted and consulted/processed with Matlab, for example. An example of Matlab usage to consult binary extension data is provided in appendix to this document.

Five binary tables have been added to the Fits file, for saving raw values from the spacecraft telemetry for later use:

1. Raw image voltages (content of telemetry packet 1304/1314);
2. ACS history raw values received from the spacecraft (packet 1306/1316);
3. CCD history (including transmitters status) (packet 1309/1319);
4. Read List raw values received from the spacecraft (packet 1303/1313); and
5. ROE telemetry (packet 1305/1315).

The next sub-sections will describe each binary table header and provide a typical example of the data that it can contain.

5.4.1 Raw Voltages Binary Table Summary

This binary table have raw byte values from the TM 1304/1314 Image Voltages.

The first column of the binary table is a 12 characters description and the second column is the corresponding raw values (a 16-bit unsigned integer/short).

Table 2 : Raw Voltages Binary Table Header

Keyword Record	Value	Description/Comments
'XTENSION'	'BINTABLE'	' Raw DAC Binary Table
'BITPIX'	8	' Manditory for BINTABLE
'NAXIS'	2	' Manditory for BINTABLE
'NAXIS1'	14	' Bytes per row
'NAXIS2'	24	' Rows in table
'PCOUNT'	0	' Manditory for BINTABLE
'GCOUNT'	1	' Manditory for BINTABLE
'TFIELDS'	2	' Fields per row
'EXTNAME'	'Raw Value'	' Extension name
'TFORM1'	'I2A'	' 12 characters
'TTYPE1'	'item name'	' Item name
'TDISP1'	'A12'	' Suggested column display
'TFORM2'	'I'	' 16-bit integer
'TZERO2'	32768	' 16-bit unsigned integer
'TUNIT2'	'adu'	' 16-bit unsigned integer
'TTYPE2'	'Raw_Value'	' Raw values
'TDISP2'	'I5'	' Suggested column display
'END'	n/a	n/a

Table 3 : Raw Voltages Binary Table Example

Description	Value
'CCDBIAS0 '	1556
'CCDBIAS1 '	1556
'CCDBIAS2 '	3712
'CCDBIAS3 '	3712
'CCDBIAS4 '	2458
'CCDBIAS5 '	2458
'CCDBIAS6 '	2627
'CCDBIAS7 '	2627
'CCDCLK00 '	0
'CCDCLK01 '	1311
'CCDCLK02 '	3448
'CCDCLK03 '	3119
'CCDCLK04 '	3119
'CCDCLK05 '	328
'CCDCLK06 '	3448
'CCDCLK07 '	328
'CCDCLK08 '	0
'CCDCLK09 '	983
'CCDCLK10 '	3448
'CCDCLK11 '	1311
'CCDCLK12 '	3448
'CCDCLK13 '	1311
'CCDCLK14 '	3448
'CCDCLK15 '	1311

5.4.2 Raw Telemetry Binary Table Summary

This binary table have raw byte values from the TM 1307/1317 Image Telemetry packet.

The first column of the binary table is a 12 characters description and the second column is the corresponding raw values (a 16-bit unsigned integer/short).

Table 4 : Raw Telemetry Binary Table Header

Keyword Record	Value	Description/Comments
'XTENSION'	'BINTABLE'	'Raw DAC Binary Table'
'BITPIX'	8	'Mandatory for BINTABLE'
'NAXIS'	2	'Mandatory for BINTABLE'
'NAXIS1'	14	'Bytes per row'

'NAXIS2'	15	' Rows in table
'PCOUNT'	0	' Mandatory for BINTABLE
'GCOUNT'	1	' Mandatory for BINTABLE
'TFIELDS'	2	' Fields per row
'EXTNAME'	'Raw Value'	' Extension name
'TFORM1'	'12A'	' 12 characters
'TTYPE1'	'item name'	' Item name
'TDISP1'	'A12'	' Suggested column display
'TFORM2'	'1I'	' 16-bit integer
'TZERO2'	32768	' 16-bit unsigned integer
'TUNIT2'	'adu'	' 16-bit unsigned integer
'TTYPE2'	'Raw_Value'	' Raw values
'TDISP2'	'I5'	' Suggested column display
'END'	n/a	n/a

Table 5 : Raw Telemetry Binary Table Example

Description	Value
'v28'	2334
'v24'	1759
'v12'	2627
'vm12'	1826
'v10'	2326
'vm10'	1741
'v5'	3066
'vm5'	748
'v5d'	3066
'v33d'	2049
'tBoard'	1857
'tPreamp'	354
'tCcd'	1113
'tPld'	2
'vTg'	720

5.4.3 ACS History Binary Table Summary

This binary table have all the raw records from the ACS history. Note that the number of row in the binary table can changed depending on the number of ACS history record that has been saved.

Table 6 : ACS history Binary Table Header

Keyword Record	Value	Description/Comments
'XTENSION'	'BINTABLE'	' ACS History Binary Table'
'BITPIX'	8	'Mandatory for BINTABLE'
'NAXIS'	2	'Mandatory for BINTABLE'
'NAXIS1'	61	'Bytes per row'
'NAXIS2'	VARIABLE	'Rows in table'
'PCOUNT'	0	'Mandatory for BINTABLE'
'GCOUNT'	1	'Mandatory for BINTABLE'
'TFIELDS'	10	'Fields per row'
'EXTNAME'	'ACS History'	'Extension name'
'TFORM1'	'1E'	'32-bit floating point'
'TTYPE1'	'Elapsed'	'Time from exposure start'
'TUNIT1'	's'	'Time value units'
'TDISP1'	'F8.3'	'Suggested column display'
'TFORM2'	'19A'	'19 characters'
'TTYPE2'	'ACS_State'	'Attitude control state'
'TDISP2'	'A19'	'Suggested column display'
'TFORM3'	'10A'	'10 characters'
'TTYPE3'	'Shutter_State'	'Shutter state'
'TDISP3'	'A10'	'Suggested column display'
'TFORM4'	'1E'	'32-bit floating point'
'TTYPE4'	'qEst[0]'	'Estimated q0'
'TUNIT4'	's'	'Value units'
'TDISP4'	'F8.3'	'Suggested column display'
'TFORM5'	'1E'	'32-bit floating point'
'TTYPE5'	'qEst[1]'	'Estimated q1'
'TUNIT5'	's'	'Value units'
'TDISP5'	'F8.3'	'Suggested column display'
'TFORM6'	'1E'	'32-bit floating point'

' TTYPE6 '	'qEst[2]'	' Estimated q2
' TUNIT6 '	's'	' Value units
' TDISP6 '	'F8.3'	' Suggested column display
' TFORM7 '	'1E'	' 32-bit floating point
' TTYPE7 '	'qEst[3]'	' Estimated q3
' TUNIT7 '	's'	' Value units
' TDISP7 '	'F8.3'	' Suggested column display
' TFORM8 '	'1E'	' 32-bit floating point
' TTYPE8 '	'wEst[0]'	' Estimated w0
' TUNIT8 '	's'	' Value units
' TDISP8 '	'F8.3'	' Suggested column display
' TFORM9 '	'1E'	' 32-bit floating point
' TTYPE9 '	'wEst[1]'	' Estimated w1
' TUNIT9 '	's'	' Value units
' TDISP9 '	'F8.3'	' Suggested column display
' TFORM10 '	'1E'	' 32-bit floating point
' TTYPE10 '	'wEst[2]'	' Estimated w2
' TUNIT10 '	's'	' Value units
' TDISP10 '	'F8.3'	' Suggested column display
' END '	n/a	n/a

Table 7 : ACS History Binary Table Example

Time from exposure start'	Attitude control state	Shutter state	qEst[0]	qEst[1]	qEst[2]	qEst[3]	wEst[0]	wEst[1]	wEst[2]
-0.152875006	'COARSE_POINT '	'OPEN '	0.57336 6463	0.81827 3008	0.02346 8034	0.03360 7192	0.00011 5008	0.00046 5731	0.00010 6655
0.047125001	'COARSE_POINT '	'OPEN '	0.57337 749	0.81826 669	0.02346 2078	0.03357 6157	0.00011 4463	0.00046 7226	0.00010 3885
0.247125	'COARSE_POINT '	'OPEN '	0.57338 8696	0.81826 0312	0.02345 5996	0.03354 5066	0.00011 3867	0.00046 8616	0.00010 1162

5.4.4 CCD & Transmitters History Binary Table Summary

This binary table have raw byte values from the TM 1309/1319 Image Telemetry packet.

The first column of the binary table represents the number of seconds since start of exposure, expressed as floating point value (4 bytes). Then, the temperature sensor reading is provided (16-bit unsigned integer, with offset of 32768, a standard for FITS data). Finally, the status of the transmitters are provided, 1 byte each (0=OFF, 1=ON).

Table 8 : CCD History Binary Table Header

Keyword Record	Value	Description/Comments
'XTENSION'	'BINTABLE'	' Raw DAC Binary Table
'BITPIX'	8	' Manditory for BINTABLE
'NAXIS'	2	' Manditory for BINTABLE
'NAXIS1'	14	' Bytes per row
'NAXIS2'	15	' Rows in table
'PCOUNT'	0	' Manditory for BINTABLE
'GCOUNT'	1	' Manditory for BINTABLE
'TFIELDS'	2	' Fields per row
'EXTNAME'	'CCD_History'	' Extension name
'TFORM1'	'IE'	' 32-bit floating point
'TTYPE1'	'Elapsed'	' Time from exposure start
'TUNIT1'	's'	' Time value unit
'TDISP1'	'F8.3'	' Suggested column display
'TFORM2'	'I'	' 16-bit integer
'TZERO2'	32768	' 16-bit unsigned integer
'TUNIT2'	'adu'	' 16-bit unsigned integer
'TTYPE2'	'Raw_Temp'	' Raw temperature sensor
'TDISP2'	'I5'	' Suggested column display
'TFORM3'	'B'	' Unsigned byte
'TTYPE3'	'TX_MY'	' Minus Y transmitter status
'TUNIT3'	'flag'	' 0=OFF, 1=ON
'TDISP3'	'I'	' Suggested column display
'TFORM4'	'B'	' Unsigned byte
'TTYPE4'	'TX_PY'	' Plus Y transmitter status
'TUNIT4'	'flag'	' 0=OFF, 1=ON
'TDISP4'	'I'	' Suggested column display
'END'	n/a	n/a

Table 9 : CCD History Binary Table Example

Elapsed	Raw_Temp	TX_MY	TX_PY
-0.502	232.1	0	0
0.502	232.0	0	0
1.502	232.3	0	0
2.502	232.2	0	0
...			

5.4.5 Read List Binary Table Summary

The table have all the Read List values used to make the Fits Image. Note that the first row of each column represent, respectively, the raw number of element in the Read List, the OP Amp Code and the Gain. After these values, it represent each field of the RD List (A,B,C). The number of row in the binary table depends on the number of RD List entry.

Table 10 : Read List Binary Table Header

Keyword Record	Value	Description/Comments
'XTENSION'	'BINTABLE'	'RDList Binary Table'
'BITPIX'	8	'Mandatory for BINTABLE'
'NAXIS'	2	'Mandatory for BINTABLE'
'NAXIS1'	6	'Bytes per row'
'NAXIS2'	Variable	'Rows in table'
'PCOUNT'	0	'Mandatory for BINTABLE'
'GCOUNT'	1	'Mandatory for BINTABLE'
'TFIELDS'	3	'Fields per row'
'EXTNAME'	'Image RDList'	'Extension name'
'TFORM1'	'I'	'16-bit integer'
'TZERO1'	32768	'16-bit unsigned integer'
'TTYPE1'	'A'	number of item then 'A''
'TFORM2'	'I'	'16-bit integer'
'TZERO2'	32768	'16-bit unsigned integer'
'TTYPE2'	'B'	opamp then 'B''
'TFORM3'	'I'	'16-bit integer'
'TZERO3'	32768	'16-bit unsigned integer'
'TTYPE3'	'C'	"gain then C ""
'END'	n/a	n/a

Table 11 : Read List Binary Table Example

RDList 'A' or rawNumberOfElement'	RDList 'B' or OP Amp code'	RDList 'C' or GAIN
15 (*)	2 (*)	0 (*)
0	1030	1
0	1072	2
0	0	0

(*) Note: The first row of the RDList binary table represent respectively the rawNumberOfElement, OpAMP Code and the Gain.